



SINGLE-PHASE DC-AC BOOST CONVERTER

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ABSTRACT

This paper describes a new power conversion circuit topology for single-phase DC-AC boost converter, based on the dc-dc boost converter. It comprises an H-bridge, fed from a single input dc source through a boosting inductor. Change of load current flow is achieved with four current-steering diodes. The proposed boost inverter configuration performs single stage power conversion, which minimizes switching losses and attains higher efficiency as compared to the conventional boost inverter. The steady-state operating principle of the power circuit configuration and control strategy are described. A multi-loop structure controller is used to ensure a high dynamic performance. Computer simulations demonstrate the feasibility of the proposed boost inverter.

Keywords: inverter, boost converted, total harmonic distortion (THD).

1. INTRODUCTION

Conventional voltage source inverters (VSI) used in photovoltaic systems (PV), uninterruptible power supply (UPS) AC motor drives and other power supply systems, need to step-up the DC input voltage. To increase the output voltage level in order to meet load requirements, DC-DC boost converter is used to provide DC bus voltage for PWM inverters. Hence, the conventional design always cascades DC-DC converter and a separate DC-AC converter. The combined losses of the two inter-connected converter units contribute to low system efficiency. The cascaded double-stage design also makes for extra parts, greater system size and weight, [1-3]. The requirement of high voltage storage battery leads to high cost and reduced reliability, since the number of storage devices increases. An alternative design was presented in [4] wherein a boost inverter topology was implemented with two DC-DC boost converters from a view of low cost as shown in figure 1 (a). This design, however, requires two boost converters to operate simultaneously in order to generate the AC output voltage. This leads to complicated control system design.

To alleviate the above shortcomings, this paper proposes a new design for high performance single-phase boost inverter based on switch-mode DC-DC boost converter, as shown in Figure 1(b). Only one boost converter operates either in the positive or negative half cycle, allowing reduced inverter size, increased efficiency and simpler controllers.

In this paper, the multi-loop feedback control strategy, [5-9], which consists of an inner current loop for regulating the inductor current and an outer voltage loop for regulating the output voltage, is employed to control the boost inverter.

In addition, the feed-forward compensation, [10-13], for disturbance rejection is introduced to make the output voltage and inductor current track their commands closely, thus the output voltage can be well regulated.

2. SYSTEM ANALYSIS

2.1 Operating principle of the boost inverter

The proposed boost inverter circuit configuration, with the controllers, is shown in figure 2. It consists of full-bridge power stage ($S_1 - S_4$), diodes ($D_1 - D_4$), inductor L , DC capacitors (C_1 and C_2), current controller, and voltage controller. The full-bridge arrangement allows direction change of the load current flow. The proposed boost inverter operates in continuous current mode (CCM) with a fixed switching frequency, as depicted in figure 3. The load is connected differentially across the two DC capacitors. By sinusoidally modulating the switch-mode DC-DC converter output voltage in each half cycle, two DC-offset voltages (v_{DC1} and v_{DC2}) are obtained across each DC capacitor and displaced mutually 180° phase shift with each other. The output voltage v_o is given by

$$v_o = v_{DC1} - v_{DC2} \quad (1)$$

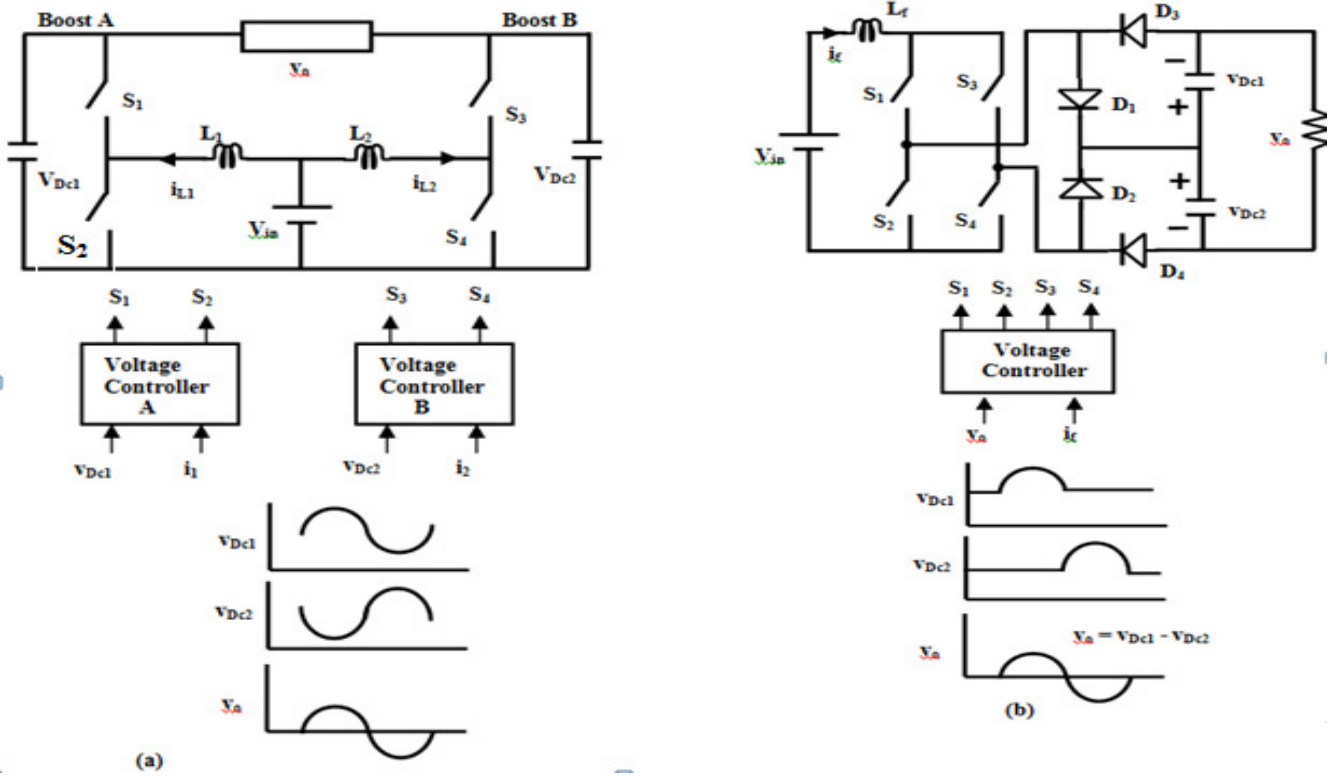


Figure 1. Boost inverter configurations: (a) Conventional boost inverter. (b) Proposed boost inverter.

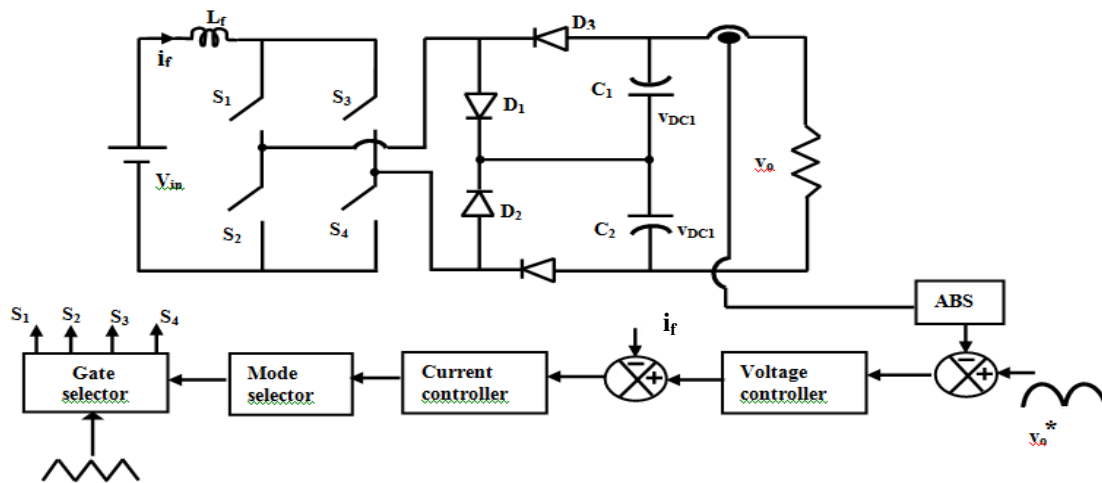


Figure 2. Power circuit and controllers for the proposed boost inverter.

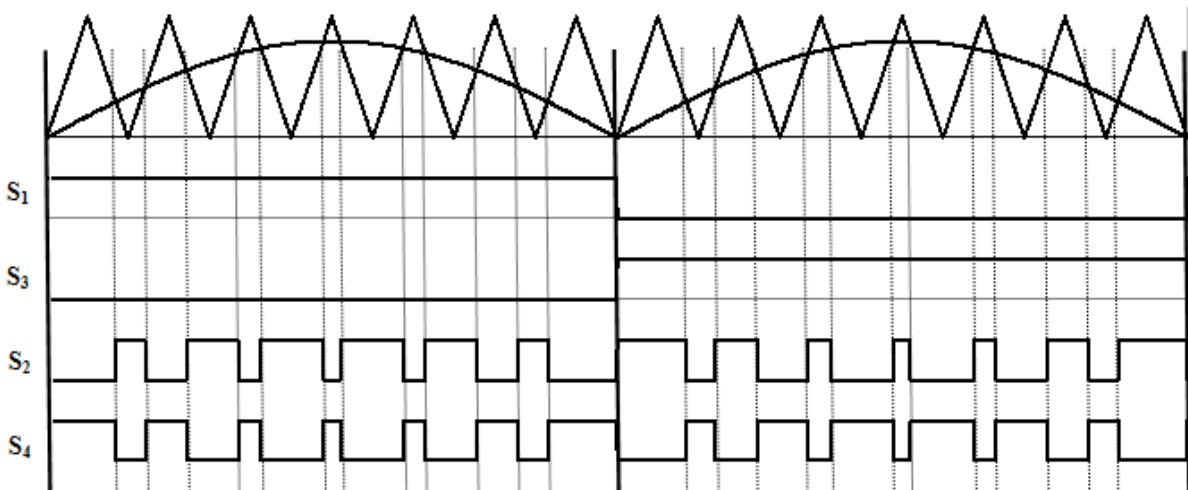


Figure 3: Simple PWM modulation scheme for the proposed boost inverter.

The operation of the boost inverter can be divided into two stages for each half cycle. Four different modes are included over one complete cycle of operation. The corresponding equivalent circuit during each mode is shown in Figure 4 and explained below.

When switches S_1 and S_2 are turned on in the positive half cycle, the inductor current increases, storing energy in the inductor. During this mode, energy stored in capacitor C_2 is transferred to the load. Next, switches S_1 and

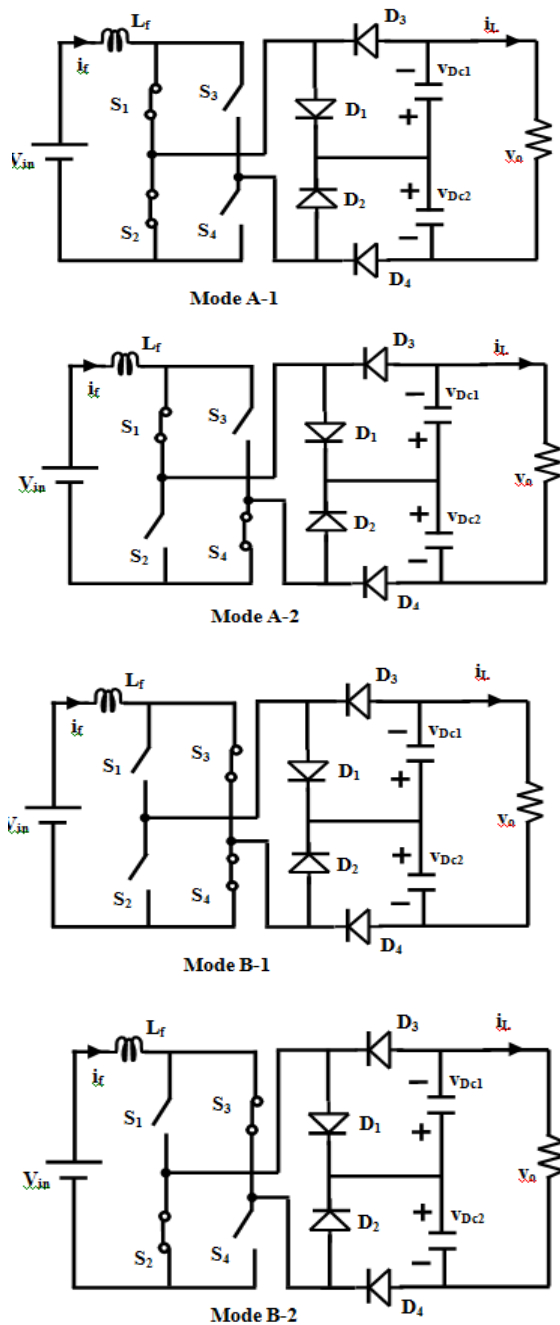


Figure 4. Modes of operation of the proposed boost inverter

The switch S_4 are turned on, the energy in the inductor is transferred to the load and capacitor C_2 through D_1

and D_4 , and thus the capacitor v_{DC2} increases. Similarly, for negative half cycles, switches S_3 and S_4 are both turned on. The inductor current increases linearly; storing energy in inductor. Meanwhile, the energy in capacitor C_1 is delivered to the load. Then, turning on S_3 and S_2 releases the energy stored in the inductor to the load and charges capacitor C_1 , through D_3 and D_2 . Table 1 shows the switching States for each operational mode.

The mode selector in figure 2 is responsible for generating the desired control signals for the power switches ($S_1 - S_4$) according to the mode switching relation given in Table 1. S_1 and S_3 operate at the fundamental frequency, changing the current direction to the load every half cycle. S_2 and S_4 are turned on and off according to the comparison between a high frequency triangular carrier signal and a rectified modulating signal. The diodes (D_1 to D_4) are used to protect the capacitors from being negatively charged. Compared to the four high frequency power switches of conventional boost inverter [1], the proposed design uses only one high frequency power switch in each half cycle. The proposed design's reduction in the number of switching operations results in significantly improved system efficiency and reliability.

Table 1: Switching states for each operational mode

Output voltage mode	$V_0 > 0$		$V_0 < 0$	
	A-1	A-2	B-1	B-2
S_1	ON	ON	OFF	OFF
S_2	ON	OFF	OFF	ON
S_3	OFF	OFF	ON	ON
S_4	OFF	ON	ON	OFF

2.2 Circuit modeling of the boost inverter

2.2.1 Mode A-1 and B-1

$$L_f \frac{di_f}{dt} = V_{in} \tag{2a}$$

$$\text{Mode A-1: } C_2 \frac{dv_{DC2}}{dt} = \frac{v_{DC1} - v_{DC2}}{R_L} \tag{2b}$$

$$\text{Mode B-1: } C_1 \frac{dv_{DC1}}{dt} = -\frac{v_{DC2} - v_{DC1}}{R_L} \tag{2c}$$

2.2.2 Mode A-2 and B-2

$$\text{Mode A-2: } L_f \frac{di_f}{dt} = V_{in} - v_{DC2} \tag{3a}$$

$$C_2 \frac{dv_{DC2}}{dt} = i_f - \frac{v_{DC2} - v_{DC1}}{R_L} \tag{3b}$$

$$\text{Mode B-2: } L_f \frac{di_f}{dt} = V_{in} - v_{DC1} \tag{4a}$$

$$C_1 \frac{dv_{DC1}}{dt} = i_f - \frac{v_{DC1} - v_{DC2}}{R_L} \tag{4b}$$

By introducing the following substitutions into (2) - (4):

$$\begin{aligned} v_o &= V_o + \widehat{v}_o \\ v_{in} &= V_{in} + \widehat{v}_{in} \\ i_f &= I_f + \widehat{i}_f \\ d &= D + \widehat{d} \end{aligned}$$

Where: V_o, V_{in}, I_f, D_o are the steady-state values of the output voltage, input voltage, inductor current and operating duty cycle, respectively; $\widehat{v}_o, \widehat{v}_{in}, \widehat{i}_f, \widehat{d}$ are the corresponding transient values.

which result in steady-state voltage and current:

$$V_o = \frac{1}{1-D} V_{in} \tag{5a}$$

$$I_f = \frac{1}{1-D} \frac{V_o}{R_L} \tag{5b}$$

Then, weighting the equations (2) - (4), the corresponding state space average modeling equations can be obtained as

$$L_f \frac{di_f}{dt} = v_{in} - v_o d' \tag{6a}$$

$$C \frac{dv_o}{dt} = i_f d' - \frac{v_o}{R_L} \tag{6b}$$

$$d = 1 - d' \tag{6c}$$

Based on (6), the time averaged circuit model of the boost inverter, [10], can be determined as shown in figure 5.

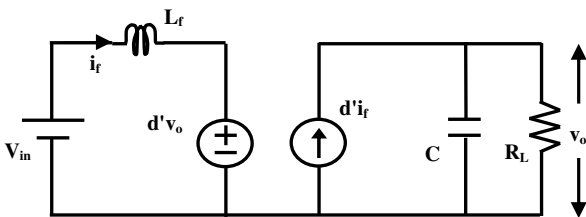
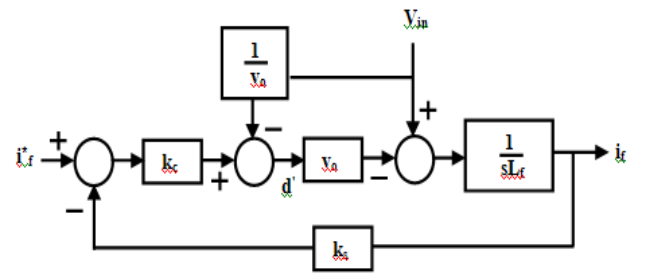


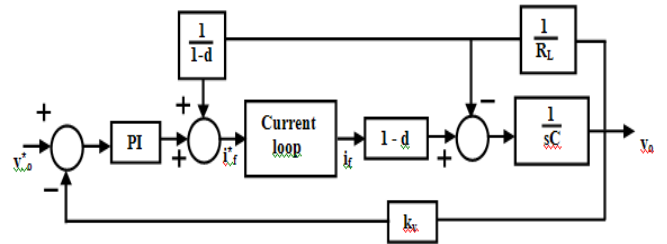
Figure 5. Average state space circuit model

2.3 Control strategy

From figure 5, the multi-loop control system block diagram of the proposed boost inverter is designed as shown in figure 6. A multi-loop controller which consists of an inner current loop and outer voltage loop is used to regulate the output voltage. A full-wave rectified signal is used to produce an AC reference voltage v_o^* . The outer voltage loop generates the reference current command i_f^* . A common proportional plus integral (PI) controller is used to regulate the output voltage. The inner current loop compares the reference current command i_f^* with the inductor current i_f . A proportional controller is used for the current loop. The output of this current loop is then compared with a triangular carrier, generating the desired gating signals for the switches. Additionally, feedback and feed-forward control techniques are employed in multi-loop to obtain desired tracking performance.



(a) Current control loop



(b) Voltage control loop

Figure 6. Control block diagram of the proposed boost inverter

3. SIMULATION RESULTS

The performance of the proposed boost inverter is verified via computer simulation. The simulations are conducted using MATLAB SIMULINK and SIMPLORER software packages. Specifications of the circuit parameters in the simulations are given in table 1

Table 2: Circuit parameter specification.

$V_{in} = 60V$
$v_o = 110 V$ rms.
$L_f = 0.7mH$
$R_{load} = 15\Omega$
$C_1 = C_2, = 220\mu f$

The simulated results for resistive and rectifier loads are given in figures 7 and 8. It shows that the output voltage can be kept closely to sinusoidal waveform with low distortion. It is also observed that the output voltage is obtained by the subtraction between two capacitor voltages, as earlier predicted. For multi-loop control system, the output voltage and current response to a step load change is also investigated by simulation and given in figure 9. The simulation results show that the output voltage can maintain sinusoidal waveform and fast response can be achieved. Furthermore, figures 10 and 11 illustrate that the harmonic contents of the output voltage can be kept at a very low level. The simulated waveforms and harmonic profiles of the output voltage evidently show that the proposed boost inverter can supply power to the load with good voltage regulation and low total harmonic distortion.

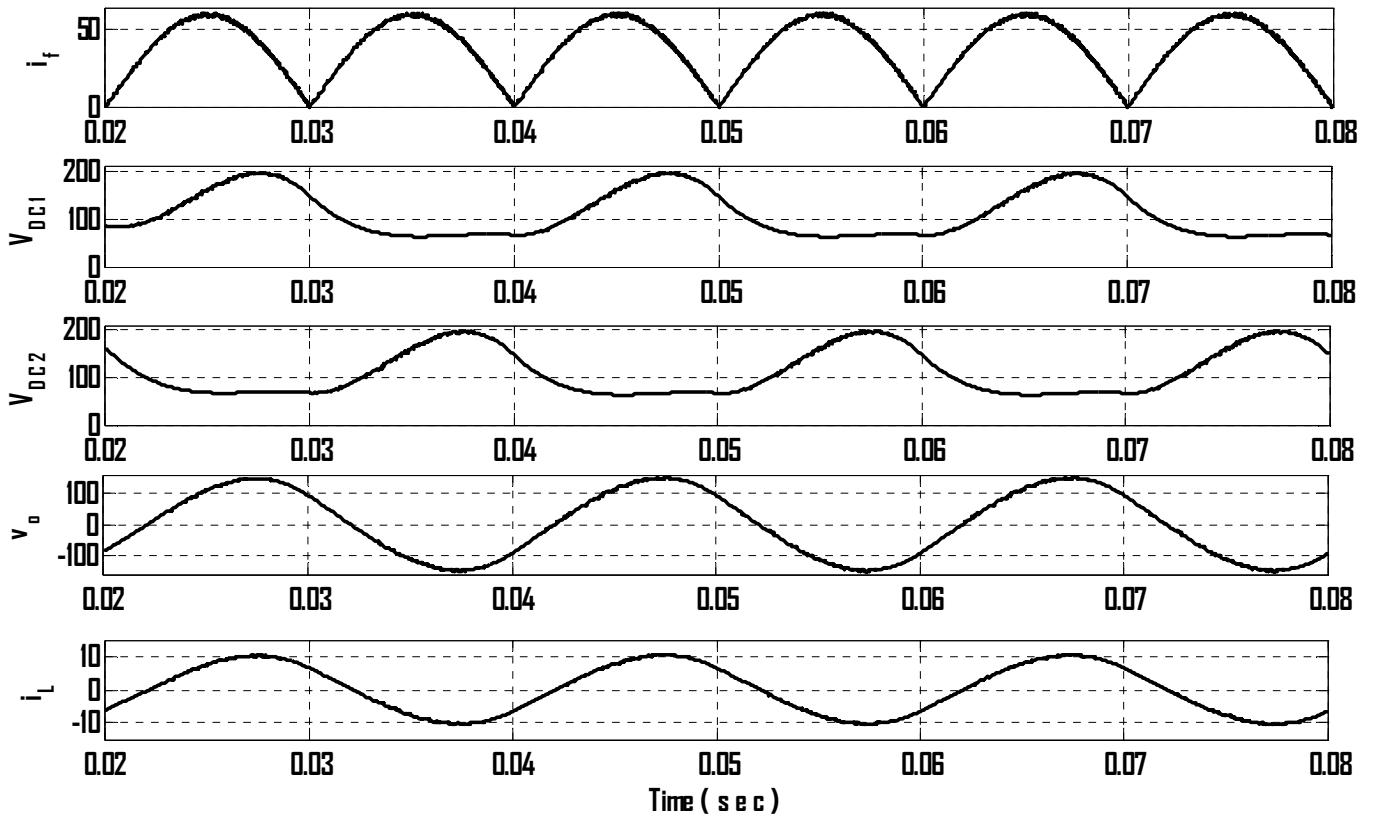


Figure 7. Simulated waveforms of resistive load.

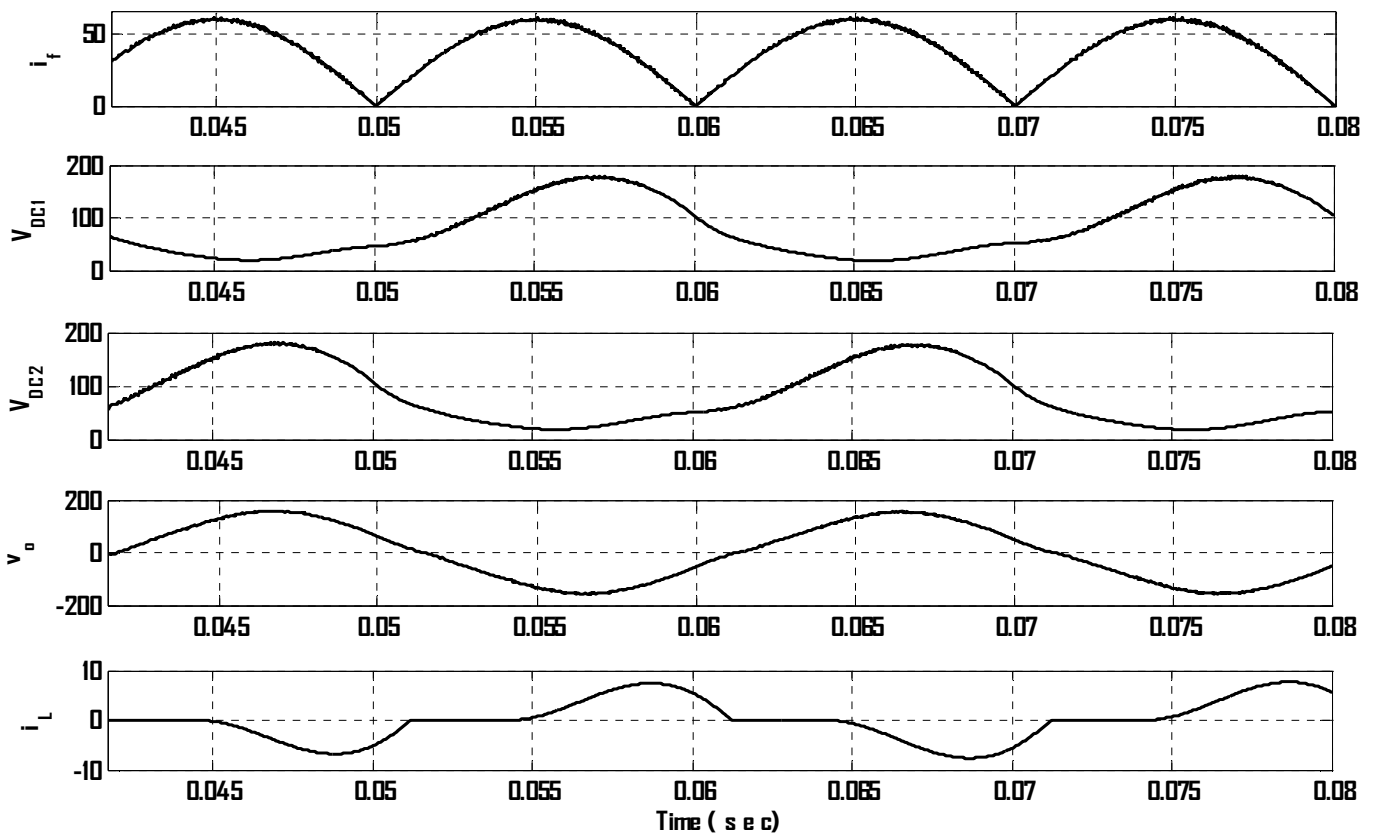


Figure 8: Simulated waveforms of rectifier load.

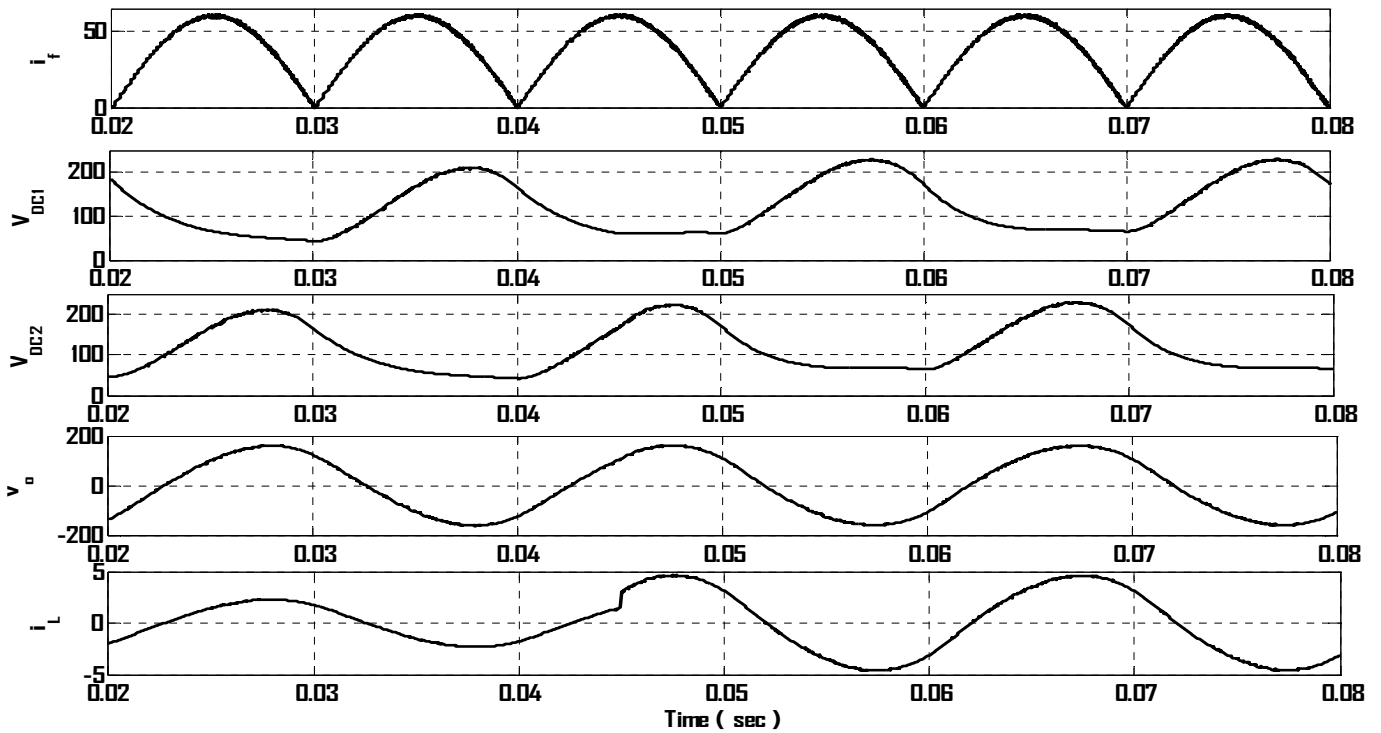


Figure 9. Simulated waveforms of output voltage and current response under step load change

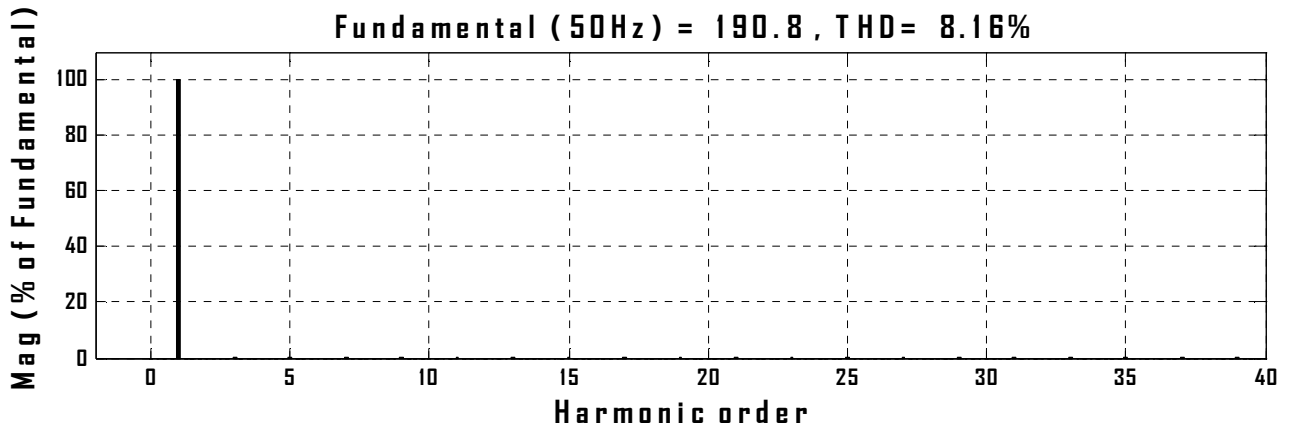


Figure 10. Simulated output voltage harmonic profile for resistive load.

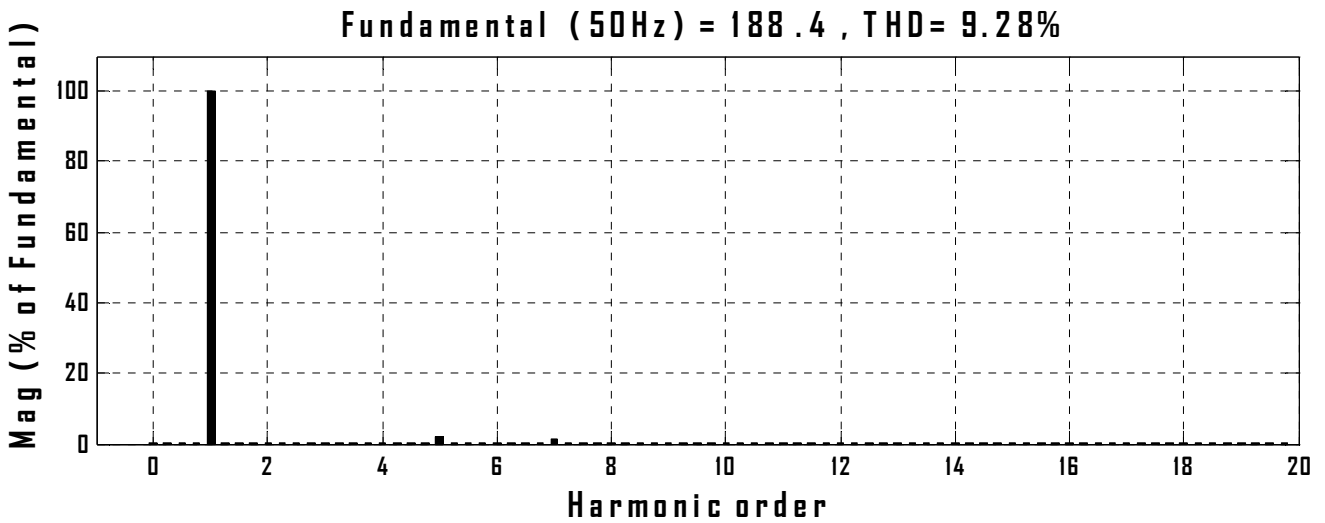


Figure 11. Simulated output voltage harmonic profile for rectifier load.

4. CONCLUSIONS

A single-phase dc-ac boost converter configuration with reduced logic system controllers has been presented. The controller has simple architecture, requiring only one voltage control system. As a result, it offers the advantages of reduced complexity of control circuit. The other advantages of the proposed boost inverter over conventional boost inverter scheme can be summarized as follows:

- (1) Simplified control scheme.
- (2) High quality sinusoidal output voltage with nonlinear load.
- (3) Reduced cost, size and weight compared to conventional systems.

Conclusively, the proposed boost inverter circuit offers a good harmonic profile and regulation of the synthesized output voltage waveform, as evidenced from the simulation study.

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