IMPOSING D-OPTIMALITY CRITERION ON THE DESIGN REGIONS OF THE CENTRAL COMPOSITE DESIGNS (CCD)

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ABSTRACT

The effect of D-optimality criterion in the construction of N-point exact designs on the design regions of the face-centered central composite design, rotatable (circumscribed) central composite design and inscribed central composite design, respectively, is investigated using a second order response surface model. Each geometric region has a finite number of support points defined by the factorial points, the axial points and the center point of the three central composite design regions. For the six parameter second order polynomial model used, the D-optimal design defined over the rotatable (circumscribed) Central Composite Design (CCD) region has better determinant values than those obtained over the face-centered central composite design region and the inscribed central composite design region. Furthermore, results indicate that D-optimal designs defined over the rotatable CCD region give better parameter estimates as the variances and covariances of the parameters are minimized.

Keywords: D-optimality criterion, face-centered CCD, inscribed CCD, circumscribed CCD

INTRODUCTION

Central Composite Designs (CCDs) play a vital role in the design of experiments. There are basically three types of CCDs, namely, the face-centered CCD, rotatable CCD and the inscribed CCD. Each CCD consists of the corner points, the axial points and the center points and these components play important roles in the estimation of model parameters. For two variates, the face-centered CCD comprises of the four corner points [(-1,-1),(1,-1),(-1,1),(1,1),four axial points [(1,0),(-1,0),(0,1),(0,-1)] and n_0 centre points [(0,0), $(0, 0), \ldots, (0, 0)$, where n_0 is the number of centre points chosen. The rotatable CCD comprises of four corner points [(-1,-1),(1,-1)] 1),(-1,1),(1,1)],four axial points [(1.414,0),(-1.414,0),(0,1.414),(0,-1.414)] and n_0 centre points $[(0,0), (0,0), \dots (0, 0)]$. The inscribed CCD comprises of four corner points [(0.7,0.7), (-0.7,0.7), (-0.7,-0.7), (0.7,-0.7)], four star points [(0, 1), (0, -1), (-1, 0), (1, 0)] and n_0 centre points $[(0,0), (0,0), \dots, (0,0)]$.

In any experimental work it is important to choose the best design in a class of existing designs. The choice is solely dependent of the interest of the experimenter and the adequacy of an experimental design can be determined from the information matrix. Many criteria exist for choosing experimental designs to meet specific

purposes, some of these criteria include orthogonality and rotatability. The orthogonality and rotatability criteria have been imposed on the three central composite designs (Box & Hunter (1957),Montgomery (1997)). In this work, we investigate the effect of imposing the Doptimality criterion on each region of the Central Composite Designs. Specifically, we explore each region of the three central composite designs to identify an N-point Doptimal exact design for a six-parameter bivariate quadratic model;

$$\begin{array}{ll} f & (x_{1,}x_{2}) & = \beta_{0} + \beta_{1}x_{1} + \beta_{2}x_{2} + \beta_{12}x_{1}x_{2} + \\ \beta_{11}x_{1}^{2} + \beta_{22}x_{2}^{2} + \epsilon. & 1.1 \end{array}$$

METHODOLOGY

As can be seen in Box and Behnken (1960), D-optimality criterion emphasizes precision of the estimated coefficients of the assumed model. The optimality criterion used in generating D-optimal designs is one of maximizing |X'X|, the determinant of the information matrix X'X. This optimality in minimizing criterion results generalized variance of the parameter estimates for a pre-specified model.Donev and Atkinson (1988) have observed that, in practice, D-optimal designs often perform well in relation to designs that are optimal by other optimality criteria. In attempting to investigate the effect of D-optimality on the regions of the Central Composite Designs (CCDs), we rely on the combinatorial algorithm of Iwundu and Chigbu (2012) which is closely related to the algorithm of Onukogu and Iwundu(2007). We however, present the algorithm more explicitly.

We assume that the \overline{N} support points that make up the experimental area have been grouped into g_1, g_2, \ldots, g_H groups. From the H groups, we shall attempt to obtain an

optimal combination of support points that shall produce D-optimal exact designs. This shall be established for N sized designs, where N ranges from p to 2p, where p is the number of model parameters. The procedure moves sequentially one step at a time in both the increasing and decreasing values of each component, r_1 , r_2 , ..., r_f ..., r_H of the groups, $g_1, g_2, \ldots, g_r, \ldots, g_H$ in the direction of increasing determinant value of the associated information matrix. The required exact D-optimum is reached and it is associated with the design class $\underline{t}_{k}^{*}=[r_{1}^{*},$ $r_2^*, \ldots, r_f^*, ..., r_H^*$, where r_i^* is the optimal number of support points taken from g_i; i=1, $2, \dots, f, \dots, H$. Let us suppose that at the k^{th} step the number of support point r_{1k} , r_{2k} , ..., $r_{fk, \dots}$, r_{Hk} are obtained from $g_1, g_2, \dots, g_r, \dots$., g_H respectively. If \underline{t}_k is the H-tuple of support points at the kth step, then the Htuple of support points at (k+1)st step is formed by holding H-2 of the rik values fixed and altering the values of the just two balls. That is, only two values of the r_{ik} are altered while the remaining H-2 values of r_{ik} are held fixed subject to $\sum r_{ik} = N$; N is the design size.

The Algorithm

We present the details of the algorithm in Tables 1 below. The table consists of sixmain columns, namely, step k, sub-step m, ball combination, number of available designs, sub-step m best determinant value and step k best determinant value. Since the algorithm aims at getting the best combination of support points that contains the D-optimal design, we shall attempt to obtain r_1^* , r_2^* ,, r_f^* ... , r_H^* , the optimal number of support points taken from g₁, g₂. . ., g_r ,... , g_H . The immediate tables shall illustrate how to obtain r_1^* . The process can be generalized for r_2^*, \ldots, r_H^* .

Table 1a:Combinatorics for Choosing D-optimal Exact Design

	ı									T	ı
		BALL COMBINATION									
Step	Sub-	$\mathbf{g_1}$	\mathbf{g}_2	\mathbf{g}_3	•••	$\mathbf{g}_{\mathbf{f}}$	•••	\mathbf{g}_{H}	Number	Sub-step m	Step k best
k	step								of	best	determinant
	m								available	determinant	value
									designs	value	
0	1	\mathbf{r}_1	\mathbf{r}_2	\mathbf{r}_3	•••	$\mathbf{r_f}$		\mathbf{r}_{H}	a ₀	$\mathbf{d_0}$	$\mathbf{d_0}$
1	1	r ₁ -1	r ₂ +1	\mathbf{r}_3	•••	$\mathbf{r_f}$	•••	$\mathbf{r}_{\mathbf{H}}$	a ₁₁₁	d_{111}^-	$\mathbf{d_1}$
	2	r ₁ -1	\mathbf{r}_2	r ₃ +1	•••	$\mathbf{r_f}$	•••	\mathbf{r}_{H}	a ₁₁₂	d_{112}^-	
		•••	•••		•••	•••	•••	•••		•••	
	H-2	r ₁ -1	\mathbf{r}_2	\mathbf{r}_3	•••	$\mathbf{r_f}$	•••	r_H+1	a _{11(H-2)}	$d_{11(H-2)}^-$	
	1	r ₁ +1	r ₂ -1	\mathbf{r}_3	•••	$\mathbf{r_f}$	•••	\mathbf{r}_{H}	a ₁₁₁	d ₁₁₁	
	2	r ₁ +1	$\mathbf{r_2}$	r ₃ -1	•••	$\mathbf{r_f}$	•••	\mathbf{r}_{H}	a ₁₁₂	d_{112}^+	
	•••	•••	•••	•••	•••		•••	•••			
	H-2	r ₁ +1	\mathbf{r}_2	r ₃	•••	$\mathbf{r_f}$	•••	r _H -1	a _{11(H-2)}	d _{11(H-2)}	
2	1	r ₁ -2	r ₂ +2	\mathbf{r}_3	•••	$\mathbf{r_f}$	•••	$\mathbf{r}_{\mathbf{H}}$	a ₂₁₁	d_{211}^-	\mathbf{d}_2
	2	r ₁ -2	r ₂ +1	r ₃ +1	•••	$\mathbf{r_f}$	•••	\mathbf{r}_{H}	a_{212}^{-}	d_{212}^-	
	•••	•••	•••	•••	•••	•••	•••	•••	•••	•••	
	H-2	r ₁ -2	r ₂ +1	r ₃	•••	$\mathbf{r_f}$	•••	r_H+1	a _{21(H-2)}	d _{21(H-2)}	
	1	r ₁ -2	r ₂ -1	r ₃ +1	•••	$\mathbf{r_f}$	•••	\mathbf{r}_{H}	a_{221}^{-}	d_{221}^-	
	2	r ₁ -2	$\mathbf{r_2}$	r ₃ +2	•••	$\mathbf{r_f}$	•••	\mathbf{r}_{H}	a_{222}^{-}	d_{222}^-	
	•••	•••	•••	•••	•••	•••	•••	•••			
	H-2	r ₁ -2	\mathbf{r}_2	r ₃ +1	•••	$r_{\rm f}$	•••	r _H +1	a _{22(H-2)}	d _{22(H-2)}	
	•••	•••	•••	•••	•••	•••	•••	•••	•••	•••	
	1	r ₁ -2	r ₂ +1	\mathbf{r}_3	•••	$\mathbf{r_f}$	•••	r_H+1	a _{2q1}	$\mathbf{d}_{2\mathbf{q}1}^{-}$	
	2	r ₁ -2	\mathbf{r}_2	r ₃ +1	•••	$\mathbf{r_f}$	•••	r_H+1	a_{2q2}^-	$\mathbf{d}_{\mathbf{2q2}}^{-}$	
		•••	•••	•••	•••	•••	•••	•••			
	H-2	r ₁ -2	\mathbf{r}_2	r ₃	•••	$\mathbf{r_f}$	•••	r_H+2	a _{2q(H-2)}	d _{2q(H-2)}	
	1	r ₁ +2	r ₂ -2	\mathbf{r}_3	•••	$\mathbf{r_f}$	•••	\mathbf{r}_{H}	a ₂₁₁	d ₂₁₁	
	2	r ₁ +2	r ₂ -1	r ₃ +1	•••	$\mathbf{r_f}$	•••	$\mathbf{r}_{\mathbf{H}}$	a ₂₁₂	d_{212}^{+}	
		•••	•••	•••	•••	•••	•••	•••		 +	
	H-2	r ₁ +2	r ₂ -1	r ₃	•••	\mathbf{r}_{f}	•••	r _H -1	a _{21(H-2)}	d _{21(H-2)}	
	1	r ₁ +2	r ₂ -1	r ₃ -1	•••	$\mathbf{r_f}$	•••	\mathbf{r}_{H}	a ₂₂₁	d ₂₂₁	
	2	r ₁ +2	\mathbf{r}_2	r ₃ -2	•••	$\mathbf{r_f}$	•••	\mathbf{r}_{H}	a ₂₂₂	d_{222}^{+}	
			•••	1	•••	•••	•••		 2 ⁺	d+ 	
	H-2	r ₁ +2	\mathbf{r}_2	r ₃ -1	•••	$\mathbf{r_f}$	•••	r _H -1	a _{22(H-2)}	d _{22(H-2)}	
				•••	•••	•••	•••	•••	••• ••	4+	
	1	r ₁ +2	r ₂ -1	r ₃	•••	$\mathbf{r_f}$	•••	r _H -1	a _{2q1}	d_{2q1}^+	
	2	r ₁ +2	\mathbf{r}_2	r ₃ -1	•••	$\mathbf{r_f}$	•••	r _H -1	a_{2q2}^+	$\mathbf{d_{2q2}^{+}}$	
			•••	•••	•••	•••	•••		 2 ⁺	d+ 	
	H-2	r ₁ +2	\mathbf{r}_2	r ₃	•••	$\mathbf{r_f}$	•••	r _H -2	$a_{2q(H-2)}^+$	$d_{2q(H-2)}^+$	
•••	•••	•••	•••	•••	•••	•••	•••	•••	•••	•••	•••

Table 1b

Step	Sub-	\mathbf{g}_1	\mathbf{g}_2	\mathbf{g}_3		$\mathbf{g}_{\mathbf{f}}$		\mathbf{g}_{H}	Number	Sub-step	Step k
k	step	81	82	8,		91		811	of	m best	best
	m								available	determina	determina
									designs	nt value	nt value
0	1	$r_1^{'}$	$r_2^{'}$	$r_3^{'}$		$\mathbf{r_f}$		$r_H^{'}$	aa ₀	d_f^*	d_f^*
1	1	$r_1' + 1$		$r_3^{'}$		r _f - 1		$r_{H}^{'}$	aa ₁₁₁	dd ₁₁₁	dd_1
	2		$r_{2}^{'}+1$	$r_3^{'}$	•••	r _f - 1	•••	$r_H^{"}$	aa ₁₁₂	dd ₁₁₂	_
	•••	•••	•••	•••	•••	•••	•••		•••	•••	
	H-1	r_1'	$r_2^{'}$	$r_3^{'}$	•••	r _f - 1	•••	$r_H^{'}+1$		$dd_{11(H-1)}^{-}$	
	1	$r_1'-1$	$r_2^{'}$	$r_{3}^{'}$	•••	$r_f + 1$	•••	$r_H^{'}$	aa ₁₁₁	dd_{111}^+	
	2	$r_{1}^{'}$	$r_{2}^{'}-1$	$\boldsymbol{r_3'}$	•••	$r_f + 1$	•••	$r_H^{'}$	aa ₁₁₂	dd^+_{112}	
	•••		•••	•••	•••	•••	•••	•••	•••	•••	
	H-1	$r_1^{'}$	$r_2^{'}$ $r_2^{'}$	$r_{3}^{'}$	•••	$r_f + 1$	•••	$r_H'-1$	aa _{11(H-1)}	$dd_{11(H-1)}^{+}$	
2	1			$r_3^{'}$	•••	r_f - 2	•••	$r_H^{'}$	aa ₂₁₁	dd_{211}^-	dd_2
	2	$r_{1}^{'}$ + 1	$r_2' + 1$	$r_3^{'}$	•••	r_f - 2	•••	$r_H^{'}$	aa ₂₁₂	dd_{212}^-	
	•••	•••	•••	•••	•••	•••	•••	•••	•••	•••	
	H-1	$r_1' + 1$	$r_2^{'}$	$r_3^{'}$	•••	r _f - 2	•••	r'_H+1	aa _{21(H-1)}	$dd_{21(H-1)}^{-}$	
	1	$r_{1}' + 1$	$r_{2}' + 1$	$r_3^{'}$	•••	r _f - 2	•••	$r_{H}^{'}$	aa ₂₂₁	dd_{221}^-	
	2	$r_1^{'}$	$r_2'+2$	$r_{3}^{'}$	•••	r_f - 2	•••	$r_H^{'}$	aa ₂₂₂	dd_{222}^-	
	•••	•••		•••	•••	•••	•••	•••	•••		
	H-1	r_1'	$r_{2}' + 1$	$r_3^{'}$	•••	r _f - 2	•••	$r'_H + 1$	aa _{22(H-1)}	$dd_{22(H-1)}^{-}$	
	•••		$r_2^{'}$	•••	•••	•••	•••		•••		
	1	$r_1' + 1$	_	$r_3^{'}$	•••	r_f - 2	•••	r'_H + 1		dd_{2q1}^{-}	
	2		$r_2' + 1$	$r_3^{'}$	•••	r_f - 2	•••	r'_H+1	aa_{2q2}^-	dd_{2q2}^{-}	
	•••	•••	•••	•••	•••	•••	•••		•••	 	
	H-1	r_1	r_2'	r_3	•••	r _f - 2	•••	$r'_H + 2$	aa _{2q(H-1)}	dd _{2q(H-1)}	
	1	r_1-2	r_2	r_3	•••	$r_f + 2$	•••			dd ⁺ ₂₁₁	
	2	r_1 - 1	$r_2^{'}-1$	$r_3^{'}$	•••	$r_f + 2$	•••			dd_{212}^+	
					•••		•••		 aa+	4d+ 	
	H-1		r_2' $r_2' - 1$	$\frac{r_3^{'}}{r_3^{'}}$	•••	$r_f + 2$			aa _{21(H-1)}		
	1		$r_2 - 1$ $r_2' - 2$	$r_3 \\ r_3'$	•••	$r_f + 2$	•••	r'_H		dd ⁺	
	2	7 1	$r_2 - z$		•••	$r_f + 2$	•••	$r_H^{'}$	aa ₂₂₂	dd ₂₂₂	
	 H-1	$r_1^{'}$	$r_2^{'}$ - 1	$r_3^{'}$	•••	$r_f + 2$	•••	$r'_{-}=1$	aa _{22(H-1)}	$dd_{22(H-1)}^+$	
					•••		•••				
	1	$r_1'-1$	$r_2^{'}$	$r_3^{'}$	•••	$r_f + 2$	•••	 r' _H - 1	aa _{2q1}	dd _{2q1}	
	2	$egin{array}{c c} r_1-1 \\ r_1' \end{array}$	r_2 $r_2'-1$	$r_3 \\ r_3^{'}$	•••		•••		aa _{2q1} aa _{2q2}	$\frac{dd_{2q1}}{dd_{2q2}^+}$	
					•••	$r_f + 2$	•••	'H-1			
	 H-1	$r_{1}^{^{\prime}}$	$r_{2}^{^{\prime}}$	$r_3^{'}$	•••	$r_f + 2$		r'_H-2	 aa _{2q(H-1)}	$dd_{2q(H-1)}^{+}$	
					•••			•			
•••	•••	•••	•••	•••	•••	•••	•••	•••	•••	•••	•••

where, step k = 0, 1, 2, ..., n, n+1, n+2, ..., q, q+1

$$d_0\!\!< d_1\!\!< d_2\!< \ldots < d_n\!\!> d_{(n+1)}$$

$$d_{(n+2)}\!\!< d_{(n+3)}\!\!< \ldots < d_q\!\!> d_{(q+1)}$$

 $d_k *= \max\{(\det M(\xi_k^{(i,j)})\}; M(\xi_k^{(i,j)}) \in S_k^{pxp}; k = 0, 1, 2, \dots, q+1$

 S_k^{pxp} is the space of non-singular pxp information matrices at the k^{th} step.

Table 1a assumes the initial tuple of support points at step 0 as

$$\underline{\boldsymbol{t}}_0 = [\mathbf{r}_1, \, \mathbf{r}_2, \, \ldots \, \mathbf{r}_f, \, \ldots, \mathbf{r}_H]$$

where

 r_1 is the initial number of support points taken from group g_1

 r_2 is the initial number of support points taken from group g_2

 r_3 is the initial number of support points taken from group g_3

•

 r_f is the initial number of support points taken from group g_f

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 r_H is the initial number of support points taken from group g_H .

The group g_f contains the r_f support points we shall hold fixed while making increments on the r_{i} 's of the other groups. By incremental changes on the r_{i} , we aim at getting the optimal number of support points taken from the H-groups namely, r_1' , r_2' , ..., $r_{H'}$ while holding r_f value fixed. We shall hereafter refer to as the conditional optimal number of supports points from g_1 as r_1' , the optimal number of support points from g_2 as

 r_2 ', etc. After defining the initial tuple of support points $\underline{\boldsymbol{t}}_0 = [r_1, r_2, \dots, r_f, \dots, r_H]$, we shall obtain the determinant value d_0 of the best design in the category or combination. Holding r_f value fixed, we proceed to obtain the optimal number of support points from a group, say, g_1 . This requires effecting an increment on r_1 value by 1. Hence, we define the 2(H-2) tuples of support points in step 1. These tuples are

$$\underline{\boldsymbol{t}}_{11} = [\mathbf{r}_1 - 1 \quad \mathbf{r}_2 + 1 \quad \mathbf{r}_3 \quad \mathbf{r}_4 \quad \dots \quad \mathbf{r}_f, \quad \dots \quad \mathbf{r}_H].$$

$$\underline{t}_{12} = [r_1-1 \qquad r_2 \quad r_3+1 \quad r_4 \dots r_f, \dots r_H].$$

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$$\underline{\boldsymbol{t}}_{1(H-2)} = [\mathbf{r}_{1}-1 \quad \mathbf{r}_{2} \quad \mathbf{r}_{3} \quad \mathbf{r}_{4} \dots \mathbf{r}_{f}, \dots \mathbf{r}_{H+1}].$$

$$\underline{\boldsymbol{t}}_{1H} = [r_1+1 \quad r_2-1 \quad r_3 \quad r_4 \quad \dots \quad r_f, \quad \dots$$

$$\underline{\boldsymbol{t}}_{1(H+1)} = [r_1+1 \quad r_2 \quad r_3-1 \quad r_4 \quad \dots \quad r_f, \quad \dots \quad r_H].$$

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$$\underline{t}_{1(2H-4)} = [r_1+1 \quad r_2 \quad r_3 \quad r_4 \quad \dots \quad r_f, \quad \dots \quad r_{H-1}].$$

At each sub-step of step 1, we compute the determinant value of information matrix associated with the best design in the category. These determinant values are, respectively, \mathbf{d}_{111}^- ,

 \mathbf{d}_{112}^- , ..., $\mathbf{d}_{11(H-2)}^-$, \mathbf{d}_{111}^+ , \mathbf{d}_{112}^+ , ..., $\mathbf{d}_{11(H-2)}^+$. Comparing these determinant values, the best determinant value in step 1 is $\mathbf{d}_1 = \max \left[\mathbf{d}_{111}^- \right]$,

 $d_{112}^- \text{ , ...,} d_{11(H-2)}^- \text{, } d_{111}^+ \text{, } d_{112}^+ \text{, ... } \text{, } d_{11(H-2)}^+].$ Suppose $d_1 < d_0$, then we have obtained the optimal value r₁ holding r_f value fixed. Thus, the best determinant when r_fis held fixed is $d_f^* = d_0$. Now, we seek to obtain r_2 holding r_f and r₁ fixed. This will require carrying out a similar process by effecting an increment on r₂ value. The process continues similarly for r_3, r_4, \ldots, r_H . Note however, that if at step 1, $d_1 > d_0$, we proceed to effect an increment on r_1 by 2. Assuming that d₁ is associated with the tuple $\underline{t}_{111} = [r_1 - 1, r_2 + 1, r_3, r_4, \dots r_f, \dots]$ r_H], increments in the decreasing direction is required. Hence, we do not need to explore all sub-steps of step 2. Incrementing r_1 by 2 is equivalent to incrementing r_1 -1 by 1. Consequently, the required tuples of support points at this iteration are

$$\begin{array}{lllll} \underline{\boldsymbol{t}}_{21} = [r_1 \text{-} 2 & r_2 \text{+} 2 & r_3 & r_4 \dots & r_f, \dots \\ & . & . & . & . \\ & . & . & . & . \\ & \underline{\boldsymbol{t}}_{22} = [r_1 \text{-} 2 & r_2 \text{+} 1 & r_3 \text{+} 1 & r_4 \dots & r_f, \dots \\ & . & . & . & . \\ & . & . & . & . \end{array}$$

 $\underline{t}_{1(H-2)} = [r_1-2 \quad r_2+1 \quad r_3 \quad r_4 \dots r_f, \dots \\ . r_{H}+1].$

As earlier observed, we shall compute the determinant value of the best designs in

each of the combinations or categories. At step 2, the best determinant value is d_2 . This value will again be compared with d_1 to check for convergence. Again if $d_2 > d_1$, we effect an increment on r_1 by 3. If otherwise, then $d_f^* = d_1$. Continuing the process will yield the tuple of support points

 $\underline{\boldsymbol{t}}_{f'}=[r_{1'},\ r_{2'},\ r_{3'},\ r_{4'},\ \dots,\ r_{f},\ \dots\ r_{H'}].$ The remaining task is that of attempting to effect increments on r_f so as to obtain the optimal number of support points r_f^* taken from group g_f . This will be achieved by defining combination of support points as in table 1b. Again at each step of the table, we shall obtain the determinant value that is associated with the information matrix of the best design. We note however, that effecting increments on r_f value will obviously affect the values of $r_1', r_2', r_3', r_4', \dots, r_{H'}$.

Consequently, the tuple that results in the global best determinant value is defined by $\underline{t}^* = [r_1^*, r_2^*, r_3^*, r_4^*, \dots, r_f^*, \dots, r_H^*], \text{ where }$ r_i* is the optimal number of support points taken from the ith group g_i , i=1, 2, ..., r, ..., H. The D-optimal exact design is contained in the immediate tuple and is associated with d*. The sequence of steps described in the algorithm presented in this work is used to obtain a D-optimal exact design defined over each of the three regions of the central composite designs. When the determinant values of the resulting D-optimal exact designs are compared, the global D-optimal exact design is that with the best determinant value of information matrix.

Exploration Using Design Region of the Face-Centered Central Composite Design

The nine design points are grouped according to their distance from the center of the design region as follows:

$$\mathbf{g_1} \!\!=\!\! \begin{bmatrix} (1 & 1) \\ (1-1) \\ (-1 & 1) \\ (-1-1) \end{bmatrix} \!\!; \; \mathbf{g_2} \!\!=\! \begin{bmatrix} (1 & 0) \\ (0 & 1) \\ (-1 & 0) \\ (0-1) \end{bmatrix} \!\!; \; \mathbf{g_3} \!\!=\! \begin{bmatrix} (0 & 0) \end{bmatrix}$$

Table 2 gives the computations involved in obtaining the required N-point D-optimal exact design defined over the region of the Face-centered CCD.

Table 2: Computations for N-Point D-Optimal Exact Design defined over the region of Face-Centered CCD

Design size N	Requ	ired combi	nation	Number of available designs	Best determinant value for the combination	Best determinant value for N-point design	
	\mathbf{g}_1	\mathbf{g}_2	\mathbf{g}_3				
6	4	1	1	4	5.486968437x10 ⁻³	5.486968437x10 ⁻³	
	4	0	2	1	Singular design	1	
	4	2	0	6	5.486968437x10 ⁻³	1	
	3	2	1	24	1.371742109 x10 ⁻³	1	
	3	1	2	16	Singular design	1	
	3	3	0	16	1.371742109 x10 ⁻³	1	
7	4	2	1	6	8.159865377 x10 ⁻³	8.159865377 x10 ⁻³	
	4	3	0	4	6.527892302 x10 ⁻³	1	
	4	1	2	4	4.351928201 x10 ⁻³	1	
	3	3	1	16	3.263946151 x10 ⁻³	1	
	3	2	2	24	2.447959613 x10 ⁻³	1	
	5	2	0	24	4.351928201 x10 ⁻³	1	
	5	1	1	16	4.351928201 x10 ⁻³	1	
8	4	3	1	4	8.7890625 x10 ⁻³	8.7890625 x10 ⁻³	
	4	4	0	1	8.7890625 x10 ⁻³		
	4	2	2	6	6.34765625 x10 ⁻³	1	
	3	4	1	4	3.845214844 x10 ⁻³	1	
	3	3	2	16	2.685546875 x10 ⁻³	1	
	3	2	3	24	1.647949219 x10 ⁻³	1	
	5	2	1	24	7.263183594 x10 ⁻³		
	5	3	0	16	5.615234375 x10 ⁻³		
9	4	3	2	4	7.225637461 x10 ⁻³	9.754610572 x10 ⁻³	
	4	4	1	1	9.754610572 x10 ⁻³		
	4	5	0	4	7.225637461 x10 ⁻³		
	5	3	1	16	8.30948308 x10 ⁻³		
	5	4	0	4	7.948201207 x10 ⁻³	1	
	3	5	1	16	3.432177794 x10 ⁻³		
	3	4	2	4	3.070895921 x10 ⁻³		
10	6	3	1	24	8.448 x10 ⁻³	9.360 x10 ⁻³	
	6	4	0	6	7.680 x10 ⁻³		
	6	2	2	36	6.528 x10 ⁻³		
	5	4	1	4	9.360 x10 ⁻³		
	5	3	2	16	7.360 x10 ⁻³	1	
	4	4	2	1	8.064 x10 ⁻³	1	
	4	5	1	4	8.064 x10 ⁻³	1	
11	6	3	2	24	7.9478 x10 ⁻³	9.5374 x10 ⁻³	
	6	4	1	6	9.5374 x10 ⁻³	1	
	6	5	0	24	7.153013642 x10 ⁻³	1	
	5	5	1	16	8.182614091 x10 ⁻³	1	
	5	4	2	4	8.182614091 x10 ⁻³	1	
	7	3	1	16	8.70644589 x10 ⁻³	1	
	7	4	0	4	7.947792936 x10 ⁻³	1	
12	7	3	2	16	8.5305 x10 ⁻³	1.0154 x10 ⁻²	
	7	4	1	4	1.0154 x10 ⁻²		
	7	5	0	16	7.630315482 x10 ⁻³		
	6	4	2	6	8.723422476 x10 ⁻³	1	
	6	5	1	24	8.610896756 x10 ⁻³	1	
	8	4	0	1	8.573388182 x10 ⁻³	1	
F	8	3	1	4	9.4307001 x10 ⁻³	1	

Exploration Using the Design Regions of the Circumscribed Central Composite Design

The nine design points are grouped according to their distance from the center of the design region as follows:

$$\mathbf{g_1} \!\!=\!\! \begin{bmatrix} (-1 - 1) \\ (1 - 1) \\ (-1 \ 1) \\ (1 \ 1) \end{bmatrix} \qquad \mathbf{g_2} \!\!=\! \begin{bmatrix} (-1.414 \ 0) \\ (1.414 \ 0) \\ (0 \ -1.414) \\ (0 \ 1.414) \end{bmatrix} \quad \mathbf{g_3} \!\!=\! [(0 \ 0)]$$

Table 3 gives the computations involved in obtaining the required N-point D-optimal exact design defined over the region of the Circumscribed CCD.

Table 3: Computations for N-Point D-Optimal Exact Design defined over the region of Circumscribed CCD

Design size N	Requ	iired co	mbination	Number of available designs	Best determinant value for the combination	Best determinant value for N-point design	
	g_1	\mathbf{g}_2	\mathbf{g}_3				
6	4	1	1	4	2.1935x10 ⁻²	3.1947 x10 ⁻²	
	4	0	2	1	Singular design		
	4	2	0	6	8.002097395 x10 ⁻⁹		
	3	2	1	24	3.1947 x10 ⁻²		
	3	1	2	16	1.917904894 x10 ⁻¹⁶		
	2	3	1	24	3.1936 x10 ⁻²		
	2	2	2	36	Singular design		
	5	0	1	4	Singular design		
	5	1	0	16	Singular design		
7	4	2	1	6	3.478652316 x10 ⁻²	3.8374 x10 ⁻²	
	4	3	0	4	1.269164043 x10 ⁻⁸	_	
	3	3	1	16	3.8374 x10 ⁻²		
	3	2	2	24	2.533875249x10 ⁻²		
	5	1	1	16	1.739720013x10 ⁻²		
	5	2	0	24	6.3467766949x10 ⁻⁹		
8	4	3	1	4	4.6828 x10 ⁻²	4.6828 x10 ⁻²	
	4	4	0	1	2.2780 x10 ⁻⁸		
	4	2	2	6	3.1226 x10 ⁻²		
	5	2	1	24	3.1057 x10 ⁻²		
	5	3	0	16	2.5969 x10 ⁻²		
	3	4	1	16	3.9613 x10 ⁻²		
	3	3	2	16	3.4444 x10 ⁻²		
9	4	3	2	4	4.6198 x10 ⁻²	6.1584 x10 ⁻²	
	4	4	1	1	6.1584 x10 ⁻²		
	4	5	0	4	1.9664 x10 ⁻²		
	3	5	1	16	4.3127 x10 ⁻²		
	3	4	2	4	4.617894753 x10 ⁻²		
	5	4	0	4	4.6179 x10 ⁻²		
	5	3	1	16	4.3146 x10 ⁻²		
10	6	3	1	24	4.2659 x10 ⁻²	6.545687882 x10 ⁻²	
	6	2	2	36	3.1542 x10 ⁻²		
	6	4	0	6	1.8289 x10 ⁻²		
	7	2	1	24	3.051961074 x10 ⁻²		
	7	3	0	16	9.705868151 x10 ⁻²		
	5	4	1	4	5.318619101 x10 ⁻²		
	5	3	2	16	4.585877357 x10 ⁻²		
	4	5	1	4	5.318124827 x10 ⁻²		
	4	4	2	1	6.545687882 x10 ⁻²		
	3	5	2	16	2.845220095 x10 ⁻²		
	3	4	3	4	3.681207836 x10 ⁻²]	

11	6	3	2	24	4.81595308 x10 ⁻²	6.004443063 x10 ⁻²
	6	4	1	6	4.849988508 x10 ⁻²	
	6	2	3	36	2.67072703 x10 ⁻²	
	6	5	0	16	1.769754112 x10 ⁻⁸	
	7	3	1	16	3.883169145 x10 ⁻²	
	7	4	0	4	1.76943802 x10 ⁻⁸	
	5	5	1	16	4.873431177 x10 ⁻²	
	5	4	2	4	6.004443063 x10 ⁻²	
	4	5	2	4	6.003885053 x10 ⁻²	
	4	4	3	1	5.542305077 x10 ⁻²	
12	7	3	2	16	4.607707551 x10 ⁻²	5.782736734 x10 ⁻²
	7	2	3	24	3.066286558 x10 ⁻²	
	7	4	1	4	4.62472377 x10 ⁻²	
	7	5	0	16	1.775025317 x10 ⁻⁸	
	8	3	1	4	3.700474095 x10 ⁻²	
	8	4	0	1	1.800109831 x10 ⁻⁸	
	6	5	1	24	4.665371273 x10 ⁻²	
	6	4	2	6	5.754920024 x10 ⁻²	
	5	5	2	16	5.782736734 x10 ⁻²	
	5	4	3	4	5.343583614 x10 ⁻²	
	4	6	2	6	5.753823369x10 ⁻²	
	4	5	3	4	5.34308702x10 ⁻²	

Exploration Using the Design Regions of the Inscribed Central Composite Design (CCD).

The nine design points are grouped according to their distance from the center of the design region as follows:

$$g_1 = \begin{bmatrix} 0 & -1 \\ -1 & 0 \\ 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} -0.7 & -0.7 \\ 0.7 & 0.7 \\ 0.7 & -0.7 \\ -0.7 & 0.7 \end{bmatrix}$$
 and $g_3 = \begin{bmatrix} 0 & 0 \end{bmatrix}$

Table 4 gives the computations involved in obtaining the required N-point D-optimal exact design defined over the region of the Face-centered CCD.

Table 4: Computations for N-Point D-Optimal Exact Design defined over the region of Inscribed CCD

Design size N	Required combination		Number of available designs	Best determinant value for the combination	Best determinant value for N-point design	
	\mathbf{g}_1	\mathbf{g}_2	\mathbf{g}_3			
6	4	1	1	4	8.23388201x10 ⁻⁵	1.166000031 x10 ⁻⁴
	4	2	0	6	1.317421122 x10 ⁻⁷	
	4	0	2	1	Singular design	
	3	0	1	4	Singular design	
	3	1	0	16	Singular design	
	2	2	1	24	1.166000031 x10 ⁻⁴	
	2	1	2	16	Singular design	
	5	3	1	24	1.138726121 x10 ⁻⁴	
	5	2	2	36	Singular design	
7	4	2	1	6	1.293061227 x10 ⁻⁴	1.384704002 x10 ⁻⁴
	4	3	0	4	2.068897963 x10 ⁻⁷	
	4	1	2	4	6.530612257 x10 ⁻⁵	
	3	3	1	16	1.384704002 x10 ⁻⁴	
	3	2	2	24	9.248000017 x10 ⁻⁵]
	2	4	1	6	1.223792642 x10 ⁻⁴	1
	2	3	2	24	9.031680016 x10 ⁻⁵	1
	5	2	0	24	1.044897961x10 ⁻⁷]

	5	1	1	16	6.530612257x10 ⁻⁵	
8	4	3	1	4	1.713104121 x10 ⁻⁴	1.713104121 x10 ⁻⁴
	4	2	2	6	1.160639648 x10 ⁻⁴	
	4	4	0	1	3.676906406 x10 ⁻⁷	
	3	4	1	4	2.872290039 x10 ⁻⁵	
	3	3	2	16	1.242783454 x10 ⁻⁴	
	5	3	0	16	1.742131836 x10 ⁻⁷	
	5	2	1	32	1.148901361 x10 ⁻⁴	
9	4	3	2	4	1.689588363 x10 ⁻⁴	2.224059802 x10 ⁻⁴
	4	4	1	1	2.224059802 x10 ⁻⁴	
	4	5	0	4	3.169409453 x10 ⁻⁷	
	4	2	3	6	8.587633994 x10 ⁻⁵	
	5	4	0	4	3.178569596 x10 ⁻⁷	
	5	3	1	16	1.579874833 x10 ⁻⁴	
	3	5	1	16	1.534964942 x10 ⁻⁴	
	3	4	2	4	1.644687632 x10 ⁻⁴	
10	6	3	1	24	1.563596968 x10 ⁻⁴	2.362949253 x10 ⁻⁴
	6	4	0	6	2.960404572 x10 ⁻⁷	
	6	2	2	36	1.167569805x10 ⁻⁴	
	5	4	1	4	1.926766644 x10 ⁻⁴	
	5	3	2	16	1.678763834x10 ⁻⁴	
	4	5	1	16	1.914833165 x10 ⁻⁴	
	4	4	2	1	2.362949253 x10 ⁻⁴	
	3	4	3	4	1.310962693 x10 ⁻⁴	
	3	5	2	16	1.631039655 x10 ⁻⁴	
11	6	3	2	24	1.764737875 x10 ⁻⁴	2.174265558 x10 ⁻⁴
	6	4	1	6	1.762975304 x10 ⁻⁴	
	6	2	3	36	9.885246831 x10 ⁻⁵	
	5	4	2	4	2.174265558 x10 ⁻⁴	
	5	3	3	16	1.421298734 x10 ⁻⁴	
	4	5	2	4	2.160796031 x10 ⁻⁴	
	4	4	3	1	2.000462835 x10 ⁻⁴	
12	7	3	2	16	1.694161158 x10 ⁻⁴	2.090927535 x10 ⁻⁴
	7	4	1	4	1.686792358 x10 ⁻⁴	
	7	2	3	24	1.135900047 x10 ⁻⁴	
	6	4	2	6	2.090927535 x10 ⁻⁴	
	6	3	3	24	1.570364948 x10 ⁻⁴	
	5	5	2	16	2.087634435 x10 ⁻⁴	
	5	4	3	4	1.934679313 x10 ⁻⁴	
	8	2	2	6	1.22684842 x10 ⁻⁴	
	8	3	1	4	1.36597303 x10 ⁻⁴	

SUMMARY

We present in tables 5 and 6 the summary of the D-optima for the three design regions and the design points of D-optimality, respectively. For easy presentation of the design points of D-optimality, we label the candidate points for the region of Facecentered CCD as follows;

For the region of Circumscribed CCD we have;

1: (1,1), 2: (1.-1), 3: (-1,1), 4: (-1,-1), 5: (1.414,0), 6: (-1.414,0), 7: (0,1.414), 8: (0,-1.414), 9: (0,0)

For the region of Inscribed CCD we have;

It is worth noting that for some N, there are equivalent designs that yield the same determinant value of imformation matrix.

Faced-CenteredCCD Design CircumscribedCCD **Inscribed CCD** Size N 5.486968437x10⁻³ 1.166000031 x10⁻⁴ 3.1947 x10⁻² 6 8.159865377 x10⁻³ 3.837429233x10⁻² 1.384704002 x10⁻⁴ 7 8.7890625 x10⁻³ 4.6828 x10⁻² 1.713104121x10⁻⁴ 8 9.754610572 x10⁻³ 9 6.1584 x10⁻² 2.224059802 x10⁻⁴ 9.360 x10⁻³ 6.545687882 x10⁻² 2.362949253 x10⁻⁴ 10 9.5374×10^{-3} 6.004443063 x10⁻² 2.174265558 x10⁻⁴ 11 12 1.0154 x10⁻² 5.782736734x10⁻² 2.090927535 x10⁻⁴

Table 5: D-optima using the regions of the three central composite designs

Table 6: Some Design points of D-optimality over the regions of the three central composite designs

Design	Faced-Co	entered CCD	Circumsc	ribedCCD	Inscribed CCD		
Size N	$g_1:g_2:g_3$	Design points	$g_1:g_2:g_3$	Design points	$g_1:g_2:g_3$	Design points	
6	4 1 1	1,2,3,4,5,9	3 2 1	1,2,3,6,8,9	3 2 1	1,2,5,6,8,9	
7	4 2 1	1,2,3,4,5,8,9	3 3 1	1,2,3,5,6,8,9	3 3 1	1,2,3,5,6,8,9	
8	4 3 1	1,2,3,4,5,6,7,9	4 3 1	1,2,3,4,5,6,7,9	4 3 1	1,2,3,4,5,6,8,9	
9	4 4 1	1,2,3,4,5,6,7,8,9	4 4 1	1,2,3,4,5,6,7,8,9	4 4 1	1,2,3,4,5,6,7,8,9	
10	5 4 1	1,2,3,4,5,6,7,8,9,1	4 4 2	1,2,3,4,5,6,7,8,9,9	4 4 2	1,2,3,4,5,6,7,8,9,9	
11	6 4 1	1,2,3,4,5,6,7,8,9,1,2	4 5 2	1,2,3,4,5,6,7,8,9,8,9	5 4 2	1,2,3,4,5,6,7,8,9,9,1	
12	7 4 1	1,2,3,4,5,6,7,8,9,1,2,3	5 5 2	1,2,3,4,5,6,7,8,9,9,1,6	6 4 2	1,2,3,4,5,6,7,8,9,9,6,7	

By imposing D-optimality criterion on the regions of the three composite designs we have obtained an Npoint D-optimal exact design for a full bivariate quadratic model. In all cases, Ddesigns obtained under optimal (Circumscribed) Rotatable Central Composite Design region had the best determinant values. Hence in estimating the parameters of the bivariate polynomial model, designs defined over the rotatable (circumscribed) central composite design region would give a more precise estimate of model parameters than those defined over face-centred inscribed or composite design regions. Also when trying to decide which CCD to use, if the experimenter's interest is in obtaining precision parameter, then thecircumscribedCCD is recommended.

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